

# Sparse Approximation via Penalty Decomposition Methods

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Joint work with Yong Zhang (SFU)

# Outline

Some sparse decision problems

Penalty decomposition methods for  $l_0$  minimization

Computational results

# Sparse least squares regression

Consider a regression model:

$$y = f(\xi, \mathbf{x}) + \eta.$$

Given a data set consisting of  $n$  points  $(\xi^i, y_i)$ ,  $i = 1, \dots, n$ , the least squares model is:

$$\min_{\mathbf{x}} \sum_{i=1}^n (y_i - f(\xi^i, \mathbf{x}))^2.$$

The sparse least squares models are:

$$\min_{\mathbf{x}} \sum_{i=1}^n (y_i - f(\xi^i, \mathbf{x}))^2 + \nu \|\mathbf{x}\|_0,$$

$$\min_{\mathbf{x}} \left\{ \sum_{i=1}^n (y_i - f(\xi^i, \mathbf{x}))^2 : \|\mathbf{x}\|_0 \leq r \right\}.$$

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$$\begin{aligned} & \min_{\mathbf{x}} \sum_{i=1}^n (y_i - f(\xi^i, \mathbf{x}))^2 + \nu \|\mathbf{x}\|_0, \\ & \min_{\mathbf{x}} \{ \sum_{i=1}^n (y_i - f(\xi^i, \mathbf{x}))^2 : \|\mathbf{x}\|_0 \leq r \}. \end{aligned}$$

# Sparse logistic regression

Given scaled samples  $\{a^1, \dots, a^n\}$  and binary outcomes  $b_1, \dots, b_n$ , the *average logistic loss* function is defined as

$$l_{\text{avg}}(v, w) := \sum_{i=1}^n \theta(w^T a^i + v b_i) / n,$$

where  $\theta$  is the *logistic loss* function

$$\theta(t) := \log(1 + \exp(-t)).$$

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# Sparse inverse covariance selection

Given a sample covariance matrix  $\hat{\Sigma}$  and a set  $\Omega$  consisting of pairs of known conditionally independent nodes, the sparse inverse covariance selection models are:

$$\max_{X \succeq 0} \left\{ \log \det X - \langle \hat{\Sigma}, X \rangle - \nu \sum_{(i,j) \in \bar{\Omega}} \|X_{ij}\|_0 : X_{ij} = 0 \quad \forall (i,j) \in \Omega \right\},$$

$$\max_{X \succeq 0} \left\{ \log \det X - \langle \hat{\Sigma}, X \rangle : X_{ij} = 0 \quad \forall (i,j) \in \Omega, \sum_{(i,j) \in \bar{\Omega}} \|X_{ij}\|_0 \leq r \right\},$$

where  $\bar{\Omega} = \{(i,j) : (i,j) \notin \Omega, i \neq j\}$ .



# $l_0$ minimization

Consider

$$\min_{\mathbf{x} \in \mathcal{X}} \{f(\mathbf{x}) : \mathbf{g}(\mathbf{x}) \leq 0, \mathbf{h}(\mathbf{x}) = 0, \|\mathbf{x}_J\|_0 \leq r\}, \quad (1)$$

$$\min_{\mathbf{x} \in \mathcal{X}} \{f(\mathbf{x}) + \nu \|\mathbf{x}_J\|_0 : \mathbf{g}(\mathbf{x}) \leq 0, \mathbf{h}(\mathbf{x}) = 0\}. \quad (2)$$

Assumption:

- ▶  $\mathcal{X}$  is a closed convex set.
- ▶  $f : \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $\mathbf{g} : \mathbb{R}^n \rightarrow \mathbb{R}^m$ ,  $\mathbf{h} : \mathbb{R}^n \rightarrow \mathbb{R}^p$  are continuously differentiable.
- ▶ A feasible point  $\mathbf{x}^{\text{feas}}$  is known.

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# Special $l_0$ minimization

## Proposition

Consider

$$\min \left\{ \phi(\mathbf{x}) = \sum_{i=1}^n \phi_i(\mathbf{x}_i) : \|\mathbf{x}\|_0 \leq r, \mathbf{x} \in \mathcal{X}_1 \times \cdots \times \mathcal{X}_n \right\}. \quad (3)$$

Suppose that

- ▶  $0 \in \mathcal{X}_i$  for all  $i$ ;
- ▶  $\tilde{\mathbf{x}}_i^* \in \text{Arg min} \{ \phi_i(\mathbf{x}_i) : \mathbf{x}_i \in \mathcal{X}_i \}$ ;
- ▶  $I^*$  is the index set corresp. to the  $r$  largest values of  $\{ \phi_i(0) - \phi_i(\tilde{\mathbf{x}}_i^*) \}_{i=1}^n$ .

Then,  $\mathbf{x}^*$  is an optimal solution of (3), where

$$\mathbf{x}_i^* = \begin{cases} \tilde{\mathbf{x}}_i^* & \text{if } i \in I^*; \\ 0 & \text{o.w.} \end{cases} \quad i = 1, \dots, n.$$

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Suppose that

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Then,  $\mathbf{x}^*$  is an optimal solution of (4), where

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# Necessary conditions for general $l_0$ min (1)

## Theorem

Assume that  $x^*$  is a local minimizer of (1). Let  $J^* \subseteq J$  be an index set with  $|J^*| = r$  such that  $x_j^* = 0$  for all  $j \in \bar{J}^* := J \setminus J^*$ .

Suppose that the Robinson condition

$$\left\{ \begin{array}{l} \left[ \begin{array}{l} g'(x^*)d - v \\ h'(x^*)d \\ (I_{\bar{J}^*})^T d \end{array} \right] : \begin{array}{l} d \in \mathcal{T}_{\mathcal{X}}(x^*), v \in \mathbb{R}^m, \\ v_i \leq 0, i \in \mathcal{A}(x^*) \end{array} \right\} = \mathbb{R}^m \times \mathbb{R}^p \times \mathbb{R}^{|\bar{J}^*| - r} \quad (5)$$

holds. Then, there exists  $(\lambda^*, \mu^*, z^*)$  together with  $x^*$  satisfying KKT conditions

$$\begin{aligned} -\nabla f(x^*) - \nabla g(x^*)\lambda^* - \nabla h(x^*)\mu^* - z^* &\in \mathcal{N}_{\mathcal{X}}(x^*), \\ \lambda_i^* &\geq 0, \lambda_i^* g_i(x^*) = 0, i = 1, \dots, m; \quad z_j^* = 0, j \in \bar{J} \cup J^*. \end{aligned} \quad (6)$$

where  $\bar{J} := \{1, \dots, n\} \setminus J$ .

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## Necessary conditions for general $l_0$ min (2)

### Theorem

Assume that  $x^*$  is a local minimizer of (2). Let

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# Sufficient conditions for general $l_0$ min

## Theorem

*Assume that  $h$ 's are affine functions, and  $f$  and  $g$ 's are convex functions. Let  $x^*$  be a feasible point of (1), and let*

*$\mathcal{J}^* = \{J^* \subseteq J : |J^*| = r, x_j^* = 0, \forall j \in J \setminus J^*\}$ . Suppose that for any  $J^* \in \mathcal{J}^*$ , there exists some  $(\lambda^*, \mu^*, z^*)$  such that KKT conditions (6) hold. Then,  $x^*$  is a local minimizer of (1).*

## Theorem

*Assume that  $h$ 's are affine functions, and  $f$  and  $g$ 's are convex functions. Let  $x^*$  be a feasible point of (2), and let*

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# PD method for general $l_0$ min (1)

Observe

$$\begin{aligned} & \min_{x \in \mathcal{X}} \{f(x) : g(x) \leq 0, h(x) = 0, \|x_J\|_0 \leq r\} \\ & \quad \quad \quad \updownarrow \\ & \min_{x \in \mathcal{X}, y \in \mathcal{Y}} \{f(x) : g(x) \leq 0, h(x) = 0, x_J - y = 0\}, \quad (8) \end{aligned}$$

where

$$\mathcal{Y} = \{y \in \mathbb{R}^{|J|} : \|y\|_0 \leq r\}.$$

Define

$$q_\rho(x, y) = f(x) + \frac{\rho}{2} (\|[g(x)]^+\|^2 + \|h(x)\|^2 + \|x_J - y\|^2) \quad \forall x, y.$$

# PD method for general $l_0$ min (1)

Observe

$$\begin{aligned} \min_{x \in \mathcal{X}} \{f(x) : g(x) \leq 0, h(x) = 0, \|x_J\|_0 \leq r\} \\ \Downarrow \\ \min_{x \in \mathcal{X}, y \in \mathcal{Y}} \{f(x) : g(x) \leq 0, h(x) = 0, x_J - y = 0\}, \end{aligned} \quad (8)$$

where

$$\mathcal{Y} = \{y \in \mathbb{R}^{|J|} : \|y\|_0 \leq r\}.$$

Define

$$q_\rho(x, y) = f(x) + \frac{\rho}{2} (\| [g(x)]^+ \|^2 + \|h(x)\|^2 + \|x_J - y\|^2) \quad \forall x, y.$$



## PD method for (1)

Choose  $\varrho_0 > 0$ ,  $\sigma > 1$ ,  $y_0^0 \in \mathcal{Y}$ ,

$\Upsilon \geq \max\{f(x^{\text{feas}}), \min_{x \in \mathcal{X}} q_{\varrho_0}(x, y_0^0)\}$ . Set  $k = 0$ .

1) Set  $l = 0$ . Find an approx. solution  $(x^k, y^k)$  to

$$\min\{q_{\varrho_k}(x, y) : x \in \mathcal{X}, y \in \mathcal{Y}\}$$

by performing:

1a) Solve  $x_{l+1}^k \in \text{Arg min}_{x \in \mathcal{X}} q_{\varrho_k}(x, y_l^k)$ .

1b) Solve  $y_{l+1}^k \in \text{Arg min}_{y \in \mathcal{Y}} q_{\varrho_k}(x_{l+1}^k, y)$ .

1c) Set  $(x^k, y^k) := (x_{l+1}^k, y_{l+1}^k)$ . If  $(x^k, y^k)$  satisfies

$$\|\mathcal{P}_{\mathcal{X}}(x^k - \nabla_x q_{\varrho_k}(x^k, y^k)) - x^k\| \leq \epsilon_k,$$

then go to step 2).

1d) Set  $l \leftarrow l + 1$  and go to step 1a).

## PD method for (1)

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$$\|\mathcal{P}_{\mathcal{X}}(x^k - \nabla_x q_{\varrho_k}(x^k, y^k)) - x^k\| \leq \epsilon_k,$$

then go to step 2).

1d) Set  $l \leftarrow l + 1$  and go to step 1a).

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then go to step 2).

1d) Set  $l \leftarrow l + 1$  and go to step 1a).

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then go to step 2).

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$$\|\mathcal{P}_{\mathcal{X}}(x^k - \nabla_x q_{\varrho_k}(x^k, y^k)) - x^k\| \leq \epsilon_k,$$

then go to step 2).

1d) Set  $l \leftarrow l + 1$  and go to step 1a).

## PD method for (1)

Choose  $\varrho_0 > 0$ ,  $\sigma > 1$ ,  $y_0^0 \in \mathcal{Y}$ ,

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$$\|\mathcal{P}_{\mathcal{X}}(x^k - \nabla_x q_{\varrho_k}(x^k, y^k)) - x^k\| \leq \epsilon_k,$$

then go to step 2).

1d) Set  $l \leftarrow l + 1$  and go to step 1a).

## PD method for (1)

- 2) Set  $\varrho_{k+1} := \sigma \varrho_k$ .
- 3) If  $\min_{x \in \mathcal{X}} q_{\varrho_{k+1}}(x, y^k) > \Upsilon$ , set  $y_0^{k+1} := x^{\text{feas}}$ . Otherwise, set  $y_0^{k+1} := y^k$ .
- 4) Set  $k \leftarrow k + 1$  and go to step 1).

end

## PD method for (1)

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- 4) Set  $k \leftarrow k + 1$  and go to step 1).

**end**

## Convergence theorem for (1)

Assume that  $\epsilon_k \rightarrow 0$ . Let  $I_k = \{i_1^k, \dots, i_r^k\}$  be a set of  $r$  distinct indices in  $\{1, \dots, |J|\}$  such that  $(y^k)_i = 0$  for any  $i \notin I_k$ , and let  $J_k = \{J(i) : i \in I_k\}$ . Suppose that  $\mathcal{X}_\Upsilon := \{x \in \mathcal{X} : f(x) \leq \Upsilon\}$  is compact. Then, the following statements hold:

- (a)  $\{(x^k, y^k)\}$  is bounded.
- (b) Suppose  $(x^*, y^*)$  is a limit point of  $\{(x^k, y^k)\}$ . Then,  $x^*$  is a feasible point of (1). Moreover, there exists a subsequence  $K$  such that  $\{(x^k, y^k)\}_{k \in K} \rightarrow (x^*, y^*)$ ,  $I_k = I^*$  and  $J_k = J^* := \{J(i) : i \in I^*\}$  for some index set  $I^* \subseteq \{1, \dots, |J|\}$  when  $k \in K$  is sufficiently large.
- (c) Let  $x^*$ ,  $K$  and  $J^*$  be defined above, and let  $\bar{J}^* = J \setminus J^*$ . Suppose that the Robinson condition (5) holds at  $x^*$  for such  $\bar{J}^*$ . Then,  $\{(\lambda^k, \mu^k, \varpi^k)\}_{k \in K}$  is bounded, where

$$\lambda^k = \varrho_k [g(x^k)]^+, \quad \mu^k = \varrho_k h(x^k), \quad \varpi^k = \varrho_k (x_j^k - y^k).$$

# Convergence theorem for (1)

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## Convergence theorem for (1)

Assume that  $\epsilon_k \rightarrow 0$ . Let  $I_k = \{i_1^k, \dots, i_r^k\}$  be a set of  $r$  distinct indices in  $\{1, \dots, |J|\}$  such that  $(y^k)_i = 0$  for any  $i \notin I_k$ , and let  $J_k = \{J(i) : i \in I_k\}$ . Suppose that  $\mathcal{X}_\Upsilon := \{x \in \mathcal{X} : f(x) \leq \Upsilon\}$  is compact. Then, the following statements hold:

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- (c) Let  $x^*$ ,  $K$  and  $J^*$  be defined above, and let  $\bar{J}^* = J \setminus J^*$ . Suppose that the Robinson condition (5) holds at  $x^*$  for such  $\bar{J}^*$ . Then,  $\{(\lambda^k, \mu^k, \varpi^k)\}_{k \in K}$  is bounded, where

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## Convergence theorem for (1) (cont'd)

Moreover, each limit point  $(\lambda^*, \mu^*, \varpi^*)$  of  $\{(\lambda^k, \mu^k, \varpi^k)\}_{k \in K}$  together with  $x^*$  satisfies the KKT conditions (6) with  $z_j^* = \varpi_i^*$  for all  $j = J(i) \in \bar{J}^*$ .

- (d) Further, if  $\|x_j^*\|_0 = r$ ,  $h$ 's are affine functions, and  $f$  and  $g$ 's are convex functions, then  $x^*$  is a local minimizer of (1).

## Convergence theorem for (1) (cont'd)

Moreover, each limit point  $(\lambda^*, \mu^*, \varpi^*)$  of  $\{(\lambda^k, \mu^k, \varpi^k)\}_{k \in K}$  together with  $x^*$  satisfies the KKT conditions (6) with  $z_j^* = \varpi_j^*$  for all  $j = J(i) \in \bar{J}^*$ .

- (d) Further, if  $\|x_j^*\|_0 = r$ ,  $h$ 's are affine functions, and  $f$  and  $g$ 's are convex functions, then  $x^*$  is a local minimizer of (1).

## Convergence theorem for (2)

Assume that  $\epsilon_k \rightarrow 0$ . Suppose that  $\mathcal{X}_\Upsilon := \{x \in \mathcal{X} : f(x) \leq \Upsilon\}$  is compact. Then, the following statements hold:

- (a)  $\{(x^k, y^k)\}$  is bounded;
- (b) Suppose  $(x^*, y^*)$  is a limit point of  $\{(x^k, y^k)\}$ . Then,  $x^*$  is a feasible point of problem (2).
- (c) Let  $(x^*, y^*)$  be defined above. Suppose that  $\{(x^k, y^k)\}_{k \in K} \rightarrow (x^*, y^*)$  for some subsequence  $K$ . Let  $J^* = \{j \in J : x_j^* \neq 0\}$ ,  $\bar{J}^* = J \setminus J^*$ . Assume that the Robinson condition (7) holds at  $x^*$  for such  $\bar{J}^*$ . Then,  $\{(\lambda^k, \mu^k, \varpi^k)\}_{k \in K}$  is bounded, where

$$\lambda^k = \varrho_k [g(x^k)]^+, \quad \mu^k = \varrho_k h(x^k), \quad \varpi^k = \varrho_k (x_J^k - y^k).$$

Moreover, each limit point  $(\lambda^*, \mu^*, \varpi^*)$  of  $\{(\lambda^k, \mu^k, \varpi^k)\}_{k \in K}$  together with  $x^*$  satisfies the KKT conditions (6) with  $z_j^* = \varpi_i^*$  for all  $j = J(i) \in \bar{J}^*$ .

- (d) Further, if  $h$ 's are affine functions, and  $f$  and  $g$ 's are convex functions, then  $x^*$  is a local minimizer of (2).



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Moreover, each limit point  $(\lambda^*, \mu^*, \varpi^*)$  of  $\{(\lambda^k, \mu^k, \varpi^k)\}_{k \in K}$  together with  $x^*$  satisfies the KKT conditions (6) with  $z_j^* = \varpi_i^*$  for all  $j = J(i) \in \bar{J}^*$ .

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Moreover, each limit point  $(\lambda^*, \mu^*, \varpi^*)$  of  $\{(\lambda^k, \mu^k, \varpi^k)\}_{k \in K}$  together with  $x^*$  satisfies the KKT conditions (6) with  $z_j^* = \varpi_i^*$  for all  $j = J(i) \in \bar{J}^*$ .

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Moreover, each limit point  $(\lambda^*, \mu^*, \varpi^*)$  of  $\{(\lambda^k, \mu^k, \varpi^k)\}_{k \in K}$  together with  $x^*$  satisfies the KKT conditions (6) with  $z_j^* = \varpi_i^*$  for all  $j = J(i) \in \bar{J}^*$ .

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Moreover, each limit point  $(\lambda^*, \mu^*, \varpi^*)$  of  $\{(\lambda^k, \mu^k, \varpi^k)\}_{k \in K}$  together with  $x^*$  satisfies the KKT conditions (6) with  $z_j^* = \varpi_i^*$  for all  $j = J(i) \in \bar{J}^*$ .

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- (b) Suppose  $(x^*, y^*)$  is a limit point of  $\{(x^k, y^k)\}$ . Then,  $x^*$  is a feasible point of problem (2).
- (c) Let  $(x^*, y^*)$  be defined above. Suppose that  $\{(x^k, y^k)\}_{k \in K} \rightarrow (x^*, y^*)$  for some subsequence  $K$ . Let  $J^* = \{j \in J : x_j^* \neq 0\}$ ,  $\bar{J}^* = J \setminus J^*$ . Assume that the Robinson condition (7) holds at  $x^*$  for such  $\bar{J}^*$ . Then,  $\{(\lambda^k, \mu^k, \varpi^k)\}_{k \in K}$  is bounded, where

$$\lambda^k = \varrho_k [g(x^k)]^+, \quad \mu^k = \varrho_k h(x^k), \quad \varpi^k = \varrho_k (x_j^k - y^k).$$

Moreover, each limit point  $(\lambda^*, \mu^*, \varpi^*)$  of  $\{(\lambda^k, \mu^k, \varpi^k)\}_{k \in K}$  together with  $x^*$  satisfies the KKT conditions (6) with  $z_j^* = \varpi_i^*$  for all  $j = J(i) \in \bar{J}^*$ .

- (d) Further, if  $h$ 's are affine functions, and  $f$  and  $g$ 's are convex functions, then  $x^*$  is a local minimizer of (2).

# Sparse logistic regression (real data)

$$\min_{\mathbf{v}, \mathbf{w}} \{ l_{\text{avg}}(\mathbf{v}, \mathbf{w}) : \|\mathbf{w}\|_0 \leq r \},$$
$$\min_{\mathbf{v}, \mathbf{w}} l_{\text{avg}}(\mathbf{v}, \mathbf{w}) + \lambda \|\mathbf{w}\|_1$$

- ▶ compare the solution quality of  $l_0$  and  $l_1$  models

**Table:** Computational results on three real data sets

Data	$p$	$n$			SLEP			PD		
			$\lambda/\lambda_{\max}$	$r$	$l_{\text{avg}}$	Error (%)	Time	$l_{\text{avg}}$	Error (%)	Time
Colon	2000	62	0.5	7	0.4398	17.74	0.2	0.4126	12.9	9.1
			0.1	22	0.1326	1.61	0.5	0.0150	0	6.0
			0.05	25	0.0664	0	0.6	0.0108	0	5.0
			0.01	28	0.0134	0	1.3	0.0057	0	5.4
lono	34	351	0.5	3	0.4804	17.38	0.1	0.3466	13.39	0.7
			0.1	11	0.3062	11.40	0.1	0.2490	9.12	1.0
			0.05	14	0.2505	9.12	0.1	0.2002	8.26	1.1
			0.01	24	0.1846	6.55	0.4	0.1710	5.98	1.7
Ad	1430	2359	0.5	3	0.2915	12.04	2.3	0.2578	7.21	31.9
			0.1	36	0.1399	4.11	14.2	0.1110	4.11	56.0
			0.05	67	0.1042	2.92	21.6	0.0681	2.92	74.1
			0.01	197	0.0475	1.10	153.0	0.0249	1.10	77.4

# Sparse logistic regression (random data)

Table: Computational results on random data sets

Size $n \times p$	$\lambda/\lambda_{\max}$	$r$	SLEP			PD		
			$l_{\text{avg}}$	Error (%)	Time	$l_{\text{avg}}$	Error (%)	Time
$1000 \times 2000$	0.9	17.0	0.6411	9.76	0.4	0.2145	8.49	9.9
	0.7	52.9	0.5090	3.96	1.0	0.0588	2.66	20.0
	0.5	96.6	0.3838	2.23	1.7	0.0060	0.02	34.9
	0.3	138.7	0.2611	1.22	2.1	0.0022	0	25.5
	0.1	192.0	0.1228	0.31	2.0	0.0013	0	16.0
$2000 \times 1000$	0.9	11.0	0.6441	11.46	0.4	0.2763	10.67	15.2
	0.7	42.8	0.5083	3.63	1.1	0.0376	1.49	38.9
	0.5	78.0	0.3776	1.65	2.0	0.0032	0	34.4
	0.3	115.5	0.2490	0.6	2.6	0.0015	0	25.3
	0.1	160.8	0.1056	0.03	3.1	0.0010	0	15.8
$1000 \times 1000$	0.9	11.7	0.6417	11.00	0.1	0.2444	9.67	2.3
	0.7	37.2	0.5086	3.95	0.2	0.0572	2.46	5.8
	0.5	67.6	0.3805	2.15	0.3	0.0060	0.01	6.2
	0.3	100.1	0.2544	0.81	0.4	0.0016	0	4.6
	0.1	137.9	0.1124	0.12	0.5	0.0011	0	3.3

# Sparse inverse covariance selection (real data)

$$\max_{X \succeq 0} \left\{ \log \det X - \langle \hat{\Sigma}, X \rangle : X_{ij} = 0 \quad \forall (i, j) \in \Omega, \sum_{(i,j) \in \bar{\Omega}} \|X_{ij}\|_0 \leq r \right\},$$

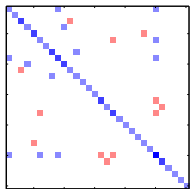
$$\max_{X \succeq 0} \left\{ \log \det X - \langle \hat{\Sigma}, X \rangle - \rho \sum_{(i,j) \in \bar{\Omega}} |X_{ij}| : X_{ij} = 0 \quad \forall (i, j) \in \Omega \right\}.$$

Table: Computational results on two real data sets

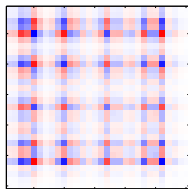
Genes $p$	Samples $n$	$\rho$	$r$	PPA			PD		
				Likelihood	Loss	Time	Likelihood	Loss	Time
587	148	0.01	144294	790.12	23.24	101.5	1035.24	22.79	38.0
		0.05	67474	174.86	24.35	85.2	716.97	23.27	31.5
		0.10	38504	-47.03	24.73	66.7	389.65	23.85	26.1
		0.50	4440	-561.38	25.52	33.2	-260.32	24.91	24.8
		0.70	940	-642.05	25.63	26.9	-511.70	25.30	22.0
		0.90	146	-684.59	25.70	22.0	-598.05	25.51	14.9
1255	72	0.01	249216	3229.75	28.25	705.7	3555.38	28.12	177.1
		0.05	169144	1308.38	29.85	491.1	2996.95	28.45	189.2
		0.10	107180	505.02	30.53	501.4	2531.62	28.82	202.8
		0.50	37914	-931.59	31.65	345.9	797.23	30.16	256.6
		0.70	4764	-1367.22	31.84	125.7	-1012.48	31.48	271.6
		0.90	24	-1465.70	31.90	110.6	-1301.99	31.68	187.8



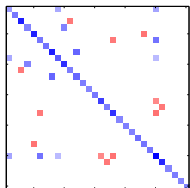
# Sparse inverse covariance selection (synthetic data)



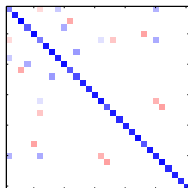
(a) True inverse  $\Sigma^{-1}$



(b) Noisy inverse  $\hat{\Sigma}^{-1}$



(c) Approximate solution of PD



(d) Approximate solution of PPA

## Summary:

- ▶ Study optimality conditions for  $l_0$  minimization
- ▶ Propose PD methods for  $l_0$  minimization
- ▶ Converge to a KKT point for general  $l_0$  minimization
- ▶ Converge to a local minimizer for “convex”  $l_0$  minimization

## Reference:

*Sparse Approximation via Penalty Decomposition Methods*  
(with Yong Zhang).

**Thank you!**

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