

Exact Support Recovery for Sparse Spikes Deconvolution

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Deconvolution

Measuring devices have a non sharp impulse response: our observations are **blurred** of a "true ideal scene".

- Geophysics,
- Astronomy,
- Microscopy,
- Spectroscopy,
- ...



Image courtesy of S. Ladjal

Goal: Obtain as much detail as we can from given measurements.

Outline

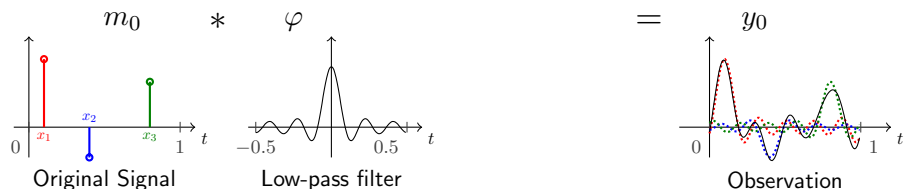
- 1 Mathematical model
- 2 Robustness for the continuous problem
- 3 Asymptotics for the discrete problems

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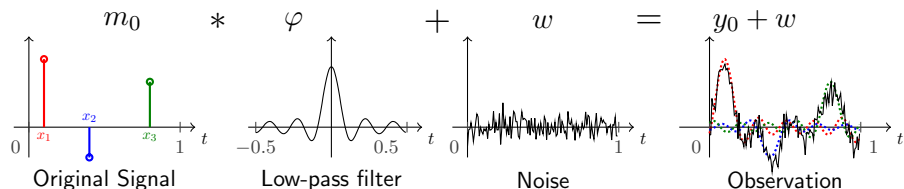
The Deconvolution Problem

Consider a signal m_0 defined on $\mathbb{T} = \mathbb{R}/\mathbb{Z}$ (i.e. $[0, 1)$ with periodic boundary condition).



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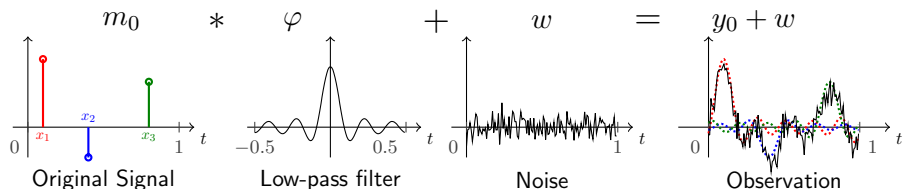
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Recovery of $m_0 = \text{Ill-posed problem}$

The Deconvolution Problem

Consider a signal m_0 defined on $\mathbb{T} = \mathbb{R}/\mathbb{Z}$ (i.e. $[0, 1)$ with periodic boundary condition).



- Assumption on the signal: m_0 is a **sparse** Radon measure

$$m_0 = \sum_{i=1}^N a_{0,i} \delta_{x_{0,i}}, \quad \text{where} \quad \begin{cases} a_{0,i} \in \mathbb{R}, \\ x_{0,i} \in \mathbb{T}, \\ N \in \mathbb{N} \text{ is small.} \end{cases}$$

so that we observe $y_0 + w = \sum_{i=1}^N a_{0,i} \varphi(\cdot - x_{0,i}) + w$.

- Idea: Look for a **sparse** signal m such that $\varphi * m \approx y_0$ (or $y_0 + w$).

Gridless Regularization

- Following (de Castro and Gamboa, 2012; Bredies and Pikkarainen, 2013; Candès and Fernandez-Granda, 2013b), we consider the continuous counterpart of the ℓ^1 norm, the **total variation of measures**:

$$\forall m \in \mathcal{M}(\mathbb{T}), \quad |m|(\mathbb{T}) = \sup \left\{ \int \psi dm ; \psi \in C(\mathbb{T}), \|\psi\|_\infty \leq 1 \right\}.$$

- ▶ if $dm = f(t)dt$, then $|m|(\mathbb{T}) = \int_{\mathbb{T}} |f(t)|dt$,
 - ▶ if $m = \sum_{i=1}^N a_i \delta_{x_i}$, then $|m|(\mathbb{T}) = \sum_{i=1}^N |a_i|$.
- Define $\Phi : \mathcal{M}(\mathbb{T}) \rightarrow L^2(\mathbb{T})$ by

$$\Phi m : t \mapsto \int_{\mathbb{T}} \varphi(x - t) dm(x).$$

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Beurling minimal extrapolation (de Castro and Gamboa, 2012)

$$\inf_{m \in \mathcal{M}(\mathbb{T})} |m|(\mathbb{T}) \text{ such that } \Phi m = y_0 \quad (\mathcal{P}_0(y_0))$$

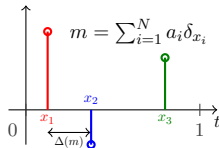
Beurling LASSO (Bredies and Pikkarainen, 2013; Azais et al., 2013)

$$\inf_{m \in \mathcal{M}(\mathbb{T})} \lambda |m|(\mathbb{T}) + \frac{1}{2} \|\Phi m - (y_0 + w)\|_2^2 \quad (\mathcal{P}_\lambda(y_0 + w))$$

Identifiability for discrete measures

Minimum separation distance of a measure m :

$$\Delta(m) = \min_{x, x' \in \text{Supp } m, x \neq x'} |x - x'|$$



Ideal Low Pass filter: $\varphi(t) = \frac{\sin(2f_c+1)\pi t}{\sin \pi t}$

i.e. $\hat{\varphi}_n = 1$ for $|n| \leq f_c$, 0 otherwise.

Theorem ((Candès and Fernandez-Granda, 2013b))

Let φ be the ideal low-pass filter. There exists a constant $C > 0$ such that, for any (discrete) measure m_0 with $\Delta(m_0) \geq \frac{C}{f_c}$, m_0 is the unique solution of

$$\inf_{m \in \mathcal{M}(\mathbb{T})} |m|(\mathbb{T}) \text{ such that } \Phi m = y \quad (\mathcal{P}_0(y))$$

where $y = \Phi m_0$.

Remark: $1 \leq C \leq 1.87$.

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Robustness of the continuous problem?

- (Bredies and Pikkarainen, 2013) the solutions to $\mathcal{P}_\lambda(y + w)$ converge to m_0 **for the weak-* topology** as $\lambda \rightarrow 0$, $\frac{\|w\|^2}{\lambda} \rightarrow 0$.
- (Azais et al., 2013): (ideal LPF) the spikes are in "boxes" around the original spikes

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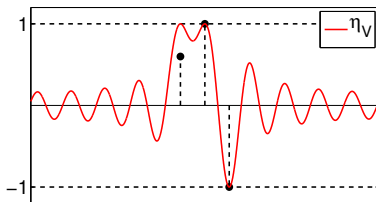
Subdifferential of the total variation

Subdifferential of the total variation

$$\begin{aligned}\partial|m|(\mathbb{T}) &= \{\eta \in C(\mathbb{T}); \quad \forall m' \in \mathcal{M}(\mathbb{T}), |m'|(\mathbb{T}) \geq |m|(\mathbb{T}) + \langle \eta, m' - m \rangle\} \\ &= \{\eta \in C(\mathbb{T}); \|\eta\|_\infty \leq 1, \forall t \in \text{Supp } m_+ \quad \eta(t) = 1, \\ &\quad \text{and } \forall t \in \text{Supp } m_- \quad \eta(t) = -1\}\end{aligned}$$

Example: For $m = \sum_{i=1}^N a_i \delta_{x_i}$,

$\partial|m|(\mathbb{T}) = \{\eta \in C(\mathbb{T}); \|\eta\|_\infty \leq 1 \text{ and } \eta(x_i) = \text{sign}(a_i) \text{ for } 1 \leq i \leq N\}$.



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Optimality conditions

- For $\mathcal{P}_0(y_0)$:

$$\exists \eta \in \partial|m_0|(\mathbb{T}) \text{ such that } \eta \in \text{Im } \Phi^*.$$

- For $\mathcal{P}_\lambda(y_0)$:

$$\exists \eta_\lambda \in \partial|m_\lambda|(\mathbb{T}) \text{ such that } \lambda \eta_\lambda + \Phi^*(\Phi m_\lambda - y_0) = 0.$$

η (resp. η_λ) is a **certificate** for m_0 (resp. m_λ), and

Find the support of m_0 (resp. m_λ) \iff Find all t such that $\eta(t) = \pm 1$ (resp. $\eta_\lambda(t) = \pm 1$)

Minimal norm certificate

Define the **minimal norm certificate** for m_0 as

$$\eta_0 = \Phi^* p_0, \quad \text{where } p_0 = \operatorname{argmin}\{\|p\|_{L^2(\mathbb{T})}; \Phi^* p \in \partial|m_0|(\mathbb{T})\}.$$

Proposition (D.P.'2013)

Let η_λ be the certificate for $\mathcal{P}_\lambda(y_0)$. Then η_λ converges to the minimal norm certificate η_0 as $\lambda \rightarrow 0^+$,

$$\lim_{\lambda \rightarrow 0^+} \eta_\lambda^{(k)} = \eta_0^{(k)}.$$

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Definition (Non Degenerate Source Condition)

We say that $m_0 = \sum_{i=1}^N a_{0,i} x_{0,i}$ satisfies the **Non Degenerate Source Condition** (NDSC) if η_0 exists (= *source condition*) and

- for all $t \in \mathbb{T} \setminus \{x_{0,1}, \dots, x_{0,N}\}$, $\eta_0(t) < 1$,
- for all $i \in \{1, \dots, N\}$, $\eta_0''(x_{0,i}) \neq 0$.

Robustness of the support

Define, for $m_0 = \sum_{i=1}^N a_{0,i} \delta_{x_{0,i}}$,

- the "matrix"

$$\Gamma_{x_0} = (\varphi(\cdot - x_{0,1}), \dots, \varphi(\cdot - x_{0,N}), \varphi'(\cdot - x_{0,1}), \dots, \varphi'(\cdot - x_{0,N})),$$

- the set $D_{\alpha, \lambda_0} = \{(\lambda, w) \in \mathbb{R} \times L^2(\mathbb{T}), 0 \leq \lambda \leq \lambda_0 \text{ and } \|w\| \leq \alpha \lambda\}$.

Robustness of the support

Theorem ((D.-P. 2013))

Let $m_0 = \sum_{i=1}^N a_i \delta_{x_{0,i}}$ such that m_0 satisfies the **Non Degenerate Source Condition** and that Γ_{x_0} has full rank. Then there exists, $\alpha > 0$, $\lambda_0 > 0$ such that on D_{α, λ_0} .

- the solution \tilde{m}_λ to $\mathcal{P}_\lambda(y + w)$ is unique and has exactly N spikes,
$$\tilde{m}_\lambda = \sum_{i=1}^N \tilde{a}_{\lambda,i} \delta_{\tilde{x}_{\lambda,i}},$$
- the mapping $(\lambda, w) \mapsto (\tilde{a}_\lambda, \tilde{x}_\lambda)$ is C^1 .

In particular, for $\lambda = \frac{1}{\alpha} \|w\|$, $|x_{0,i} - \tilde{x}_{\lambda,i}| = \mathcal{O}(\|w\|)$ and $|a_{0,i} - \tilde{a}_{\lambda,i}| = \mathcal{O}(\|w\|)$ for $1 \leq i \leq N$.

How to check the Non Degenerate Source Condition?

Let $m_0 = \sum_{i=1}^N a_{i,0} x_{i,0}$, and define the vanishing derivatives precertificate:

$$\eta_V = \Phi^* \Gamma_x^{+,*} \begin{pmatrix} s \\ 0_N \end{pmatrix},$$

where $s = (\text{sign}(a_{0,i}))_{1 \leq i \leq N}$ and $0_N = (0, \dots, 0)^T \in \mathbb{R}^N$.

Proposition (Non Degenerate Source Condition)

m_0 satisfies the **Non Degenerate Source Condition (NDSC)** if and only if

- for all $t \in \mathbb{T} \setminus \{x_{0,1}, \dots, x_{0,N}\}$, $\eta_V(t) < 1$,
- for all $i \in \{1, \dots, N\}$, $\eta_V''(x_{0,i}) \neq 0$.

In that case $\eta_0 = \eta_V$.

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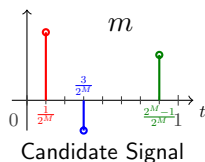
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Discretization

Define a finite grid

$\mathcal{G}_M = \{\frac{k}{2^M}; 0 \leq k \leq 2^M - 1\} \subset \mathbb{T}$, and impose that the support of the solution is on the grid

$$m = \sum_{k=0}^{2^M-1} b_k \delta_{\frac{k}{2^M}}.$$



- **Basis Pursuit** (Chen and Donoho, 1994)

$$\inf_{m \in \mathcal{M}(\mathbb{T})} |m|(\mathbb{T}) \text{ such that } \Phi m = y_0 \quad \text{and} \quad \text{Supp } m \subset \mathcal{G}_M$$

$(\mathcal{P}_0^M(y_0))$

- **LASSO** (Tibshirani, 1996) or **Basis Pursuit Denoising** (Chen et al., 1999)

$$\inf_{m \in \mathcal{M}(\mathbb{T})} \lambda |m|(\mathbb{T}) + \frac{1}{2} \|\Phi m - (y_0 + w)\|_2^2 \quad \text{and} \quad \text{Supp } m \subset \mathcal{G}_M$$

$(\mathcal{P}_\lambda^M(y_0 + w))$

Robustness

- ℓ^2 -robustness (Grasmair et al. (2011))
- Support recovery
 - ▶ **Exact Recovery Principle (ERC)** (Tropp, 2006)
 - ▶ **Weak Exact Recovery Principle (W-ERC)** (Dossal and Mallat, 2005)
 - ▶ **Fuchs criterion** (Fuchs, 2004)

Fuchs theorem

For $m_0 = \sum_{i=1}^N a_{i0} \delta_{x_{i,0}}$, define

$\eta_F = \Phi^* p_F$, where

$$\begin{aligned} p_F &= \operatorname{argmin}\{\|p\|_{L^2(\mathbb{T})}; (\Phi^* p)(x_{0,i}) = \operatorname{sign}(a_{i,0})\} \\ &= \Phi^{+,*} s. \end{aligned}$$

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Theorem (Fuchs (2004))

Assume that $\{\varphi(\cdot - x_{0,1}), \dots, \varphi(\cdot - x_{0,N})\}$ has full rank.

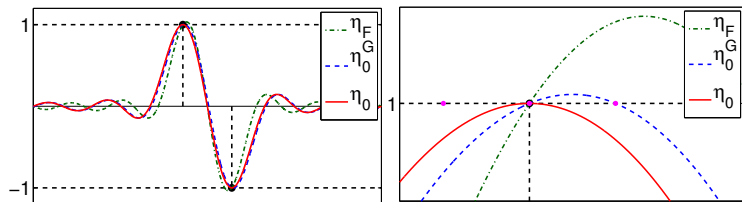
If $|\eta_F(\frac{k}{2^M})| < 1$ for all k such that $\frac{k}{2^M} \notin \{x_{0,1}, \dots, x_{0,N}\}$, then m_0 is the unique solution to $\mathcal{P}_0^M(y)$, and there exists $\alpha > 0$, $\lambda_0 > 0$ such that for $0 \leq \lambda \leq \lambda_0$ and $\|w\|_2 \leq \alpha\lambda$,

- The solution m_λ^M to $\mathcal{P}_\lambda^M(y + w)$ is unique.
- $\operatorname{Supp} m^M = \operatorname{Supp} m_0$, that is $m_\lambda^M = \sum_{i=1}^N a_{\lambda,i}^M \delta_{x_{0,i}}$, and $(\operatorname{sign} a_{\lambda,i}^*) = \operatorname{sign} a_{0,i}$,
- $a_{\lambda,I}^M = a_{0,I} + \Phi_{x_I}^+ w - \lambda(\Phi_{x_I}^* \Phi_{x_I})^{-1} \operatorname{sign}(a_{0,I})$.

If $|\eta_F(\frac{k}{2^M})| > 1$ for some k , the support is not stable.

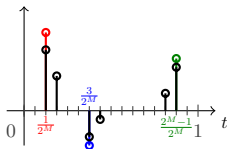
Fuchs criterion is not valid for thin grids

- η_F interpolates the sign
- Fuchs criterion: $|\eta_F(\frac{k}{2^M})| < 1$ for all k such that $\frac{k}{2^M} \notin \{x_{0,1}, \dots, x_{0,N}\}$



In general, the support **cannot be stable** for thin grids, but...

Almost-robustness of the support



Theorem ((D.-P. 2013))

Let $m_0 = \sum_{i=1}^N a_{0,i} \delta_{x_{0,i}}$ be a discrete measure, such that $x_{0,i} \in \{\frac{k}{2^M}, 0 \leq k \leq 2^M - 1\}$. Assume that m_0 satisfies the **Non Degenerate Source Condition**. Then, for M large enough, there exists, $\alpha^M > 0$, $\lambda_0^M > 0$ such that for $(\lambda, w) \in D_{\alpha^M, \lambda_0^M}$, for all m_λ^N solution of $\mathcal{P}_\lambda^N(y_0 + w)$,

$$\text{Supp } m_\lambda^N \subset \bigcup_{i=1}^N \{x_{0,i}, x_{0,i} + \frac{\varepsilon}{2^M}\} \text{ where } \varepsilon_i \in \{-1, 0, +1\}.$$

The support for small noise is made at most of **pairs of consecutive spikes**: the original one and one of its immediate neighbours.

Conclusion

- Support recovery for the continuous problem.
- Asymptotics of the discrete problems: “almost robustness” of the support
- Experiment yourself the Sparse Spikes Deconvolution on Numerical tours!

www.numerical-tours.com

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